

Technology Supplier and Service Provider

Hilscher Gesellschaft für Systemautomation mbH

- › netX ASIC technology for fieldbus and Real-Time Ethernet

Your contact: PROFdrive@hilscher.com



Siemens

- › ERTEC Asic Technology, integration support, trainings and technical support

Your contact: PROFdrive.industry@siemens.com



HMS Industrial Networks

- › PROFINET, PROFdrive, PROFIsafe & PROFInergy connectivity solutions

Your contact: PROFdrive@hms-networks.de



MESCO

- › Customer specific hardware / software development for drives, PROFIsafe and Functional Safety

Your contact: info@mesco-engineering.com



ESYSE

- › Succeeded in designing of Embedded Systems with highly integrated hard- and software solutions including PROFINET, PROFIBUS etc.

Your contact: PROFdrive@esyse.com



Please find further information about the Community Project on the PI Webseite:



www.profibus.com/PROFdriveCommunityProject

Contact:

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Community Project



Your way to PROFdrive & Encoder

Community Project

On the basis of a so called „Community Project“, the responsible workinggroup offers a base implementation of the actual PROFIdrive Profile in Source Code, **free of charge and licence** to all interested users and members of the technology.

Three Application Classes (AC) are defined and handled in the Community Project:

- › AC1 - Frequency converter
- › AC3 - Drives with positioning function
- › AC4 - Synchronous servo applications

This development represents a de facto standard reference implementation for drive technology.

Current existing Hardware Platforms

Devices:

The PROFIdrive and Encoder Layer for devices on PROFINET is available on a lot of different platforms:

- › Anybus (HMS)
- › ERTEC (Siemens, Renesas)
- › FPGA (Softing)
- › netX-Family (Hilscher)
- › SIL3 Design Package (MESCO)

Controller:

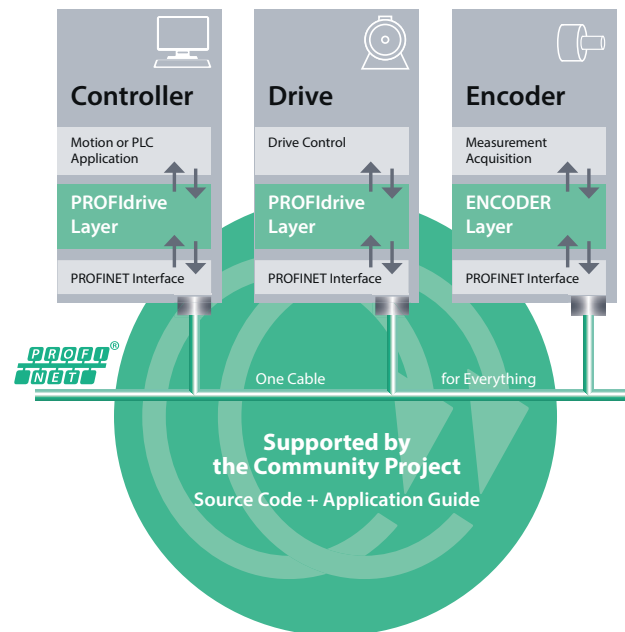
Also the PROFIdrive Profile for Controller on PROFINET is available for:

- › ERTEC (Siemens, Renesas)
- › netX-Family (Hilscher)
- › More will come

How to Implement

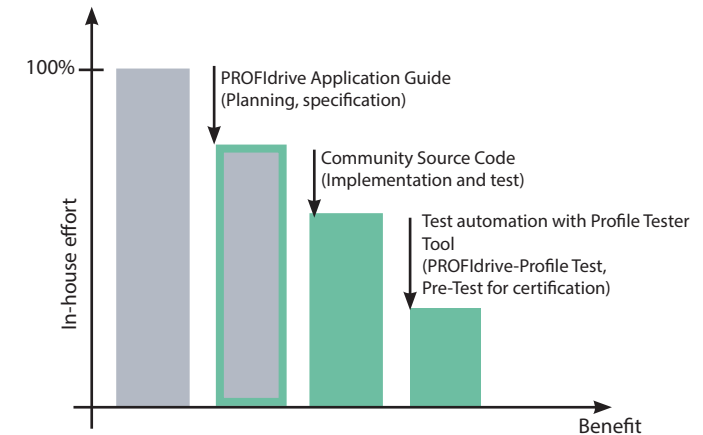
How to plan and start the implementation with best practice:

1. Define your requirements
2. Check the requirements, based on the „PROFIdrive Implementation Guide“
3. Check the PROFIdrive Profile Source Code
4. The Decision for „make or buy“
5. Setup the PROFIdrive Profile Tester
6. Start the implementation
 - a. Telegram 1 (AC1, Speed control)
 - b. Telegram 2 (AC1 + IRT)
 - c. Telegram 3 (AC4, Encoder channel)
 - d. Telegram 5 (AC4 + DSC)
 - e. Telegram 105 (AC4 + DSC + Torque control)



Your Benefits

Reduce the cost of implementation



What is available at the Community Project

- › PROFIdrive Implementation Guide AC1 + AC4
- › PROFIdrive Profile Device Source Code
 - › Drive Application Class 4 + Encoder Class 3
- › PROFIdrive Profile Controller Source Code)
 - › PROFIdrive Controller AC1
 - › PROFIdrive Controller AC4
 - › PROFIdrive Controller Isochronous Operation
- › Version overview
 - › Change log
 - › Release notes